

## 【Document Name】 Claims

## 【Claim 1】

A constant velocity universal joint comprising: an outer member which is provided with a spherical inner surface in which a plurality of track grooves are formed; an inner member which is provided with a spherical outer surface in which a plurality of track grooves are formed, balls disposed in a wedge-shaped ball track which is formed by the synergy between the track groove of the outer member and the track groove of the inner member; a retainer disposed between the spherical inner surface of the outer member and the spherical outer surface of the inner member to hold the balls, and preload means always making the balls contact to the ball tracks, wherein: the ball track is open to one of axial directions in the shape of a wedge; a pocket of the retainer has corner round sections; and a ratio (R/d) between a radius of curvature R of the corner round section and a diameter d of the torque transmission ball is  $R/d \geq 0.22$ .

## 【Claim 2】

A constant velocity universal joint according to claim 1, wherein the ratio (R/d) between the radius of curvature R of the corner round section and the diameter d of the torque transmission ball is  $0.45 \leq R/d \leq 0.62$ .

## 【Claim 3】

A constant velocity universal joint for steering according to claim 1, wherein lengths of a plurality of pockets corresponding to a plurality of the track grooves in a circumferential direction of a window are all equal.

【Document Name】 Specification

【Title of the invention】 CONSTANT VELOCITY UNIVERSAL JOINT

【Technical Field】

【0001】

The present invention relates to a constant velocity universal joint being enabled to transmit rotational torque in constant velocity even when a drive shaft and a driven shaft make an operation angle. Constant velocity universal joints are roughly classified into a fixed-type constant velocity universal joint that only allows angle variation and a slide-type constant velocity universal joint that allows angle variation as well as axial displacement. The present invention relates to the former or a fixed-type constant velocity universal joint.

【Background of the invention】

【0002】

Fig. 8 shows a fixed-type constant velocity universal joint (Rzeppa-type constant velocity universal joint: ball fixed joint) which is conventionally used as a coupling joint of a drive shaft and the like in an automobile. The constant velocity universal joint comprises: an outer member 11 in which six curved track grooves 11b are formed in a spherical inside diameter surface 11a thereof in an axial direction; an inner joint member 12 in which six curved track grooves 12b are formed in a spherical outside diameter surface 12a in the axial direction, and an engagement section 12c having teeth (serrations or splines) are formed in an inside diameter surface thereof; six torque transmission balls 13 which are disposed in respective six ball tracks, which are formed by the synergy between the track grooves 11b of the outer member 11 and the track grooves 12b of the inner joint member 12 corresponding to the track grooves 11b; and a retainer 14 which has pockets 14c for holding the torque transmission balls 13.

【0003】

The center A of the track groove 11b of the outer member 11 with respect to the spherical center of the inside diameter surface 11a and the center B of the

track groove 12b of the inner joint member 12 with respect to the spherical center of the outside diameter surface 12a are offset oppositely to each other (the center A is offset on the side of an opening of the joint, and the center B is offset on the side of a deeper side of the joint in an example shown in the drawing) at the same distance in the axial direction. Thus, the ball track, which is formed by the synergy between the track groove 11b and the track groove 12b corresponding thereto, is in the shape of a wedge opening to one of the axial directions (on the side of the opening of the joint in the example shown in the drawing). Both of the spherical center of the inside diameter surface 11a of the outer member 11 and the spherical center of the outside diameter surface 12a of the inner joint member 12 are in a joint center plane 0 including the center of the torque transmission ball 13.

【0004】

Even if the outer member 11 is displaced from the inner joint member 12 at an angle  $\theta$ , the torque transmission balls 13 guided by the retainer 14 are always maintained in a bisector plane ( $\theta/2$ ) of the angle  $\theta$  at any operating angle  $\theta$ , and hence the constant velocity of the joint is ensured.

【0005】

In this kind of fixed-type constant velocity universal joint, by the way, there are clearances between the track groove of the outer member and the ball and between the track groove of the inner member and the ball by the reasons of function and processing. This track clearance appears when one of the inner member and the outer member is fixed in a neutral state of the joint, and the other one is moved in the axial direction or is rotated in a circumferential direction.

【0006】

The track clearance has large effect on the wobbliness (rotation backlash) between the inner member and the outer member in the circumferential direction. Since the track clearance is indispensable in the fixed-type constant velocity universal joint for the reasons of processing tolerance and assembly, the

rotational backlash becomes large. Accordingly, it is concerned that using the joint as a steering joint for the automobile as-is may cause deterioration in steering operability in the vicinity of straight-ahead driving of a vehicle and the occurrence of unusual noise.

【0007】

As means to solve this problem, a fixed-type constant velocity universal joint is proposed in which preload means provided inside the joint fills an axial clearance caused by the track clearance in order to restrain the rotational backlash (refer to, for example, Patent Document 1).

【Patent Document 1】 : Japanese Patent Laid-Open

【Disclosure of the Invention】

【Problems intended to be solved by the invention】

【0008】

Fig. 9 shows the retainer 14 of the constant velocity universal joint described above. The retainer 14 has six window-shaped pockets 14c for holding the torque transmission balls 13 in circumferentially equidistant positions. Both circumferential sides of the pocket 14c are pillar sections 14d. Generally, the pockets 14c of the retainer 14 were cut by press, and then a pair of axial walls 14c1 {refer to Fig. 9(b)} opposed in the axial direction was subjected to finishing processing by shaving (broach). In this case, the axial initial clearance between the pocket 14c and the torque transmission ball 13 is set at  $-50\ \mu\text{m}$  to  $-10\ \mu\text{m}$  by processing the axial walls 14c1. If there are variations in a processing margin of the axial wall 14c1, however, the center positions of the pockets 14c are misaligned among the pockets 14c arranged in the circumferential direction, so that the so-called pocket staggered state occurs and the strength and durability of the retainer 14 become worse. Therefore, a radius of curvature R in corner round sections 14c3 of the pocket 14c is made small, and straight sections 14c4 are left. The axial dimension  $\delta$  between the axial wall 14c1 and the straight section 14c4 is controlled to prevent the occurrence of the so-called pocket staggered state.

Accordingly, making the radius of curvature R of the corner round section 14c3 small results in the extension of a pocket area to an originally functionally unnecessary part.

【0009】

Accordingly, since the pocket area is too large for its function, the pillar sections of the retainer are under high stress. The surface areas of an inside diameter surface and an outside diameter surface become small, so that there is concern that the enough strength and durability of the retainer cannot be ensured.

【0010】

In the constant velocity universal joint having preload means for always making the balls contact to the ball tracks, an object of the present invention is to optimize pocket structure without impairing the function of the retainer in order to increase the strength and durability of the retainer, and by extension the strength and durability of the joint.

【Means to solve the problems】

【0011】

To solve the foregoing object, a constant velocity universal joint according to the eighth invention of this application comprises: an outer member which is provided with a spherical inner surface in which a plurality of track grooves are formed; an inner member which is provided with a spherical outer surface in which a plurality of track grooves are formed; balls disposed in a wedge-shaped ball track which is formed by the synergy between the track groove of the outer member and the track groove of the inner member; and a retainer disposed between the spherical inner surface of the outer member and the spherical outer surface of the inner joint member to hold the balls. The ball always makes contact with the ball track by preload applying means. In such a constant velocity universal joint, the ball track is open to one of axial directions in the shape of a wedge. A pocket of the retainer has corner round sections, and a ratio ( $R/d$ ) between a radius of curvature R of the corner round section and a diameter d of the torque

transmission ball is  $R/d \geq 0.22$ .

【0012】

The reason why the ratio ( $R/d$ ) is in the foregoing range is as follows. Fig. 6 shows the results of FEM analysis indicating the relationship between the ratio ( $R/d$ ) and a maximum principal stress load applied to a pillar section (an interval section between the pockets adjoining in a circumferential direction). From the results shown in the drawing, it was recognized that a diagram of  $\{(R/d) - (\text{maximum principal stress load})\}$  took a minimum value at  $R/d = 0.537$ . It was confirmed that the maximum principal stress load of the pillar section was theoretically minimized at  $R/d = 0.537$ .

As shown in Table 1, on the basis of the analysis results, an R dimension satisfying  $R/d = 0.537$  was obtained at each size of the torque transmission ball.

Furthermore, since the general tolerance (general tolerance: when classification of standard dimensions exceeds 6 mm, allowable tolerance is  $\pm 1$  mm) of the R dimension is  $\pm 1$  mm, the maximum value and the minimum value of the R dimension were obtained, and then the maximum value and the minimum value of  $R/d$  corresponding to each value were obtained (the typical value of  $R/d$  was an average value of the maximum value and the minimum value). As a result,  $0.45 \leq R/d \leq 0.62$  was obtained as the desirable range of  $R/d$ . On the other hand, a conventional retainer shown in Fig. 9 satisfies  $R/d = 0.21$ , and the reduction effect of the maximum principal stress load can be expected at  $R/d \geq 0.22$ .

Therefore, the ratio ( $R/d$ ) was set in a range of  $R/d \geq 0.22$ , and more preferably in a range of  $0.45 \leq R/d \leq 0.62$ . Setting the ratio ( $R/d$ ) in the foregoing range makes it possible to minimize pocket space without impairing the function (operability to the torque transmission balls) of the retainer, and hence it is possible to increase the surface areas of an inside diameter surface and an outside diameter surface of the retainer. Accordingly, it is possible to increase the strength and durability of the retainer in cooperation with the reduction effect of the maximum principal stress load in the pillar section.

【0013】

【Table 1】

ball diameter (d)	R dimension			R/d		
	0.537d	maximum value※	minimum value※	upper limit	medium	lower limit
12.7	6.8	7.8	5.8	0.614	0.535	0.457
14.287	7.7	8.7	6.7	0.609	0.539	0.469
15.081	8.1	9.1	7.1	0.603	0.537	0.471
15.875	8.5	9.5	7.5	0.598	0.535	0.472
16.669	9	10	8	0.6	0.54	0.48
17.462	9.4	10.4	8.4	0.596	0.538	0.481
18	9.7	10.7	8.7	0.594	0.539	0.483
19.05	10.2	11.2	9.2	0.588	0.535	0.483
19.844	10.7	11.7	9.7	0.59	0.539	0.489
20.638	11.1	12.1	10.1	0.586	0.538	0.489
※general tolerance : $\pm 1$ (exceeds R6)				0.58 ~ 0.614	0.535 ~ 0.54	0.457 ~ 0.496

【0014】

The present invention provides a structure in which the pocket of the retainer has corner round sections, and the ratio (R/d) between the radius of curvature R of the corner round section and the diameter d of the torque transmission ball is  $R/d \geq 0.22$ , and more preferably  $0.45 \leq R/d \leq 0.62$ . This invention may be applied to a constant velocity universal joint with a straight section which has a straight fillet in each track groove of the outer member and the inner joint member. The other matters are the same as those in the constant velocity universal joint of the invention described above.

【0015】

In the constant velocity universal joint according to the present invention, the torque transmission balls are integrated as follows. Relatively varying the angle between the outer member and the inner member, in such a state

that the pocket of the retainer faces to the outside from an opening section of the outer member on one side, the torque transmission ball is integrated into the pocket of the retainer and the ball track. When the angle between the outer member and the inner member relatively varies, the torque transmission balls held in the pockets of the retainer relatively move in the circumferential direction. Thus, it is necessary to set the circumferential length of the pockets of the retainer in such a manner that the already integrated torque transmission ball relatively moving in the circumferential direction does not interfere with circumferential walls of the pocket of the retainer during integrating the torque transmission balls (the displacement angle between the outer member and the inner member at this time is called "ball integration angle" ).

**【 0 0 1 6 】**

Since the six pockets of the retainer can be composed of one kind of pocket, the circumferential lengths thereof are the same. Setting the ratio ( $R/d$ ) at a value in the foregoing range, as described above, can improve the strength and durability of the retainer, so that it is also possible to equalize the circumferential lengths of all six pockets (the same length as the foregoing second pocket).

**【 0 0 1 7 】**

Of the walls of the pocket of the retainer, it is preferable that at least a pair of axial walls opposed in an axial direction of the retainer are formed by cutting after heat treatment of the retainer. "Cutting" here includes grinding, cutting by quenched steel, and the like. Accordingly, since variations in a processing margin of the axial wall are reduced, it is possible to eliminate a straight section, which is provided in conventional pocket structure to control the processing margin of the axial wall. Thus, it is possible to increase the radius of curvature of the corner round section, and hence set the ratio ( $R/d$ ) at a value in the foregoing range.

**【 Advantage of the invention 】**



【0018】

According to the present invention, the structure of the pocket can be optimized without impairing the function of the retainer, so that it is possible to increase the strength and durability of the retainer, and by extension the strength and durability of the joint.

【BEST MODE FOR CARRYING OUT THE INVENTION】

【0019】

The embodiment of the present invention will be described in detail with reference to the drawings.

【0020】

The embodiment of a fixed-type constant velocity universal joint according to the present invention will be described in detail. The embodiment described below takes a case where the present invention is applied to a Rzeppa-type (BJ), being a kind of fixed-type constant velocity universal joint for steering joints, as an example. The present invention, however, is not limited to that, and is also applicable to an undercut free joint (UJ). A constant velocity universal joint according to the present invention is available for not only steering but also a drive shaft and a propeller shaft.

【0021】

First, a steering device in which the fixed-type constant velocity universal joint is installed will be explained in brief. The steering device, as shown in Figs. 7(a) to (c), transmits the rotational motion of a steering wheel 66 to a steering gear 68 through a steering column being composed of one or a plurality of steering shafts 62 for the purpose of converting the rotational motion into the reciprocating motion of a tie rod 69. In the case where the steering shafts 62 cannot be disposed in a straight line due to mounting space or the like, one or a plurality of shaft couplings 61 is disposed between the steering shafts 62 so as to be able to transmit correct rotational motion to the steering gear 68 even in a state of bending the steering shafts 62. In the embodiment of the present

invention, the fixed-type constant velocity universal joint is used as the shaft coupling 61. A symbol  $\alpha$  in Fig. 7(b) represents a bend angle of the joint, and a large bend angle exceeding  $30^\circ$  can be set.

**【0022】**

Fig. 1 shows a fixed-type constant velocity universal joint of the present invention. The constant velocity universal joint of this embodiment is configured to include: an outer member 1 being an outer joint member in which six curved track grooves 1a are formed in a spherical inside diameter surface 1b in an axial direction; an inner joint member 2 in which six curved track grooves 2a are formed in a spherical outside diameter surface 2b in the axial direction, and an engagement section 2d having teeth (serrations or splines) for coupling the connecting shaft 5 are formed in an inside diameter surface; six torque transmission balls 3 disposed in six ball tracks which are formed by the synergy between the track grooves 1a of the outer member 1 and the track grooves 2a of the inner joint member 2 corresponding to the track grooves 1a; and a retainer 4 which holds the torque transmission balls 3. An axial end section of the connecting shaft 5 as a drive shaft engages with the engagement section 2d of the inner joint member 2 with teeth (serration engagement or spline engagement). The inner joint member 2 and the connecting shaft 5 compose an inner member 6.

**【0023】**

The center  $O_1$  of the track groove 1a of the outer member 1 with respect to the spherical center of the inside diameter surface 1b and the center  $O_2$  of the track groove 2a of the inner joint member 2 with respect to the spherical center of the outside diameter surface 2b are offset oppositely to each other (the center  $O_1$  is on the side of an opening of the joint, and the center  $O_2$  is on a deeper side of the joint in an example shown in the drawing) at the same distance (F) in the axial direction. Thus, the ball track, which is formed by the synergy between the track groove 1a and the track groove 2a corresponding thereto, is in the shape of

a wedge opening to one of the axial directions (on the side of the opening of the joint in the example shown in the drawing).

【0024】

Both of the spherical center of an outside diameter surface 4b of the retainer 4 and the spherical center of the inside diameter surface 1b of the outer member 1 being a guide surface of the outside diameter surface 4b of the retainer 4 are in a joint center plane 0 including the center  $O_3$  of the ball 3. Also, both of the spherical center of an inside diameter surface 4c of the retainer 4 and the spherical center of the outside diameter surface 2b of the inner joint member 2 being a guide surface of the inside diameter surface 4c of the retainer 4 are in the joint center plane 0. Accordingly, the foregoing offset amount (F) of the outer member 1 is the axial distance between the center  $O_1$  of the track groove 1a and the joint center plane 0. The foregoing offset amount (F) of the inner joint member 2 is the axial distance between the center  $O_2$  of the track groove 2a and the joint center plane 0, and hence both offset amounts are equal.

【0025】

In the fixed-type constant velocity universal joint A, as shown in Figs. 1 a plunger unit 50 is attached to an axial end of the connecting shaft 5 connected to the steering shaft through the yoke 40 in order to restrain rotational backlash. The plunger unit 50 is an assembly which comprises a ball 53 being a press member having a press section 52 in its end, a compression coil spring 54 being an elastic member, and a case 55 being a container member for containing the ball 53 and the compression coil spring 54. The compression coil spring 54 is a source of elastic force which presses the ball 53 on the deeper side of the outer member 1 (in a ball protruding direction).

【0026】

The structure of attaching the foregoing plunger unit 50 to the connecting shaft 5 is as follows.

【0027】

The plunger unit 50, as shown in Fig. 2, is fixed when its case 55 is press-fitted or bonded to a recessed section 5a formed in the axial end of the connecting shaft 5. When the case 55 is completely fixed, a flange 55b of the case 55 engages with an axial end surface 5b of the connecting shaft 5, so that the position of the plunger unit 50 is fixed with reference to the axial end surface 5b. In other words, it is possible to fix the position of the plunger unit 50 if there are variations in the depth of the recessed section 5a of the connecting shaft 5 due to its processing tolerance, because the depth of the recessed section 5a is larger than the axial length of the case 55 of the plunger unit 50 and the flange 55b engages with the axial end surface 5b of the connecting shaft 5.

【 0 0 2 8 】

The case 55 of the plunger unit 50 is in the shape of a cylinder with a bottom, and an engaged section 55a protruding on the side of an inside diameter is provided at the edge of its opening end. Since the inside diameter  $\phi d$  of the engaged section 55a is smaller than the outside diameter  $\phi D$  of the ball 53, it is possible to prevent the ball 53 from dropping off. Accordingly, the ball 53, the compression coil spring 54, and the case 55 are assembled into a unit. As to means for providing an engaged section to prevent the ball 53 from dropping off, various structures are available in addition to forming the engaged section 55a by swaging the edge of the opening end of the case 55 along the whole circumference.

【 0 0 2 9 】

As shown in Figs. 2 and 3, a receiver member 56 is attached to an end section of the retainer 4 on the deeper side of the outer member 1. The receiver member 56 is in the shape of a lid covering an opening at an end of the retainer 4, and is composed of a spherical section 56a in a partial spherical shape and an attachment section 56b formed in the outer periphery of the spherical section 56a in the shape of a ring. The inner surface (surface opposed to the connecting shaft 5) of the spherical section 56a is a concave spherical surface which functions as the receiving section 58 for receiving pressure from the press section 52. The

attachment section 56b is fixed in the end of the retainer 4 by proper means such as press or welding.

【0030】

To smoothly slide the press section 52 of the plunger unit 50 on the receiving section 58 of the receiver member 56 when the connecting shaft 5 of the constant velocity universal joint takes an operating angle, as shown in Fig. 3, the inside diameter  $R_o$  of the receiving section 58 in a recessed spherical shape is set larger than the outside diameter ( $\phi D/2$ ) (refer to Fig. 2) of the ball 53 having the press section 52 ( $R_o > (\phi D/2)$ ). To prevent the interference between the receiver member 56 and the inner joint member 2 in taking an operating angle  $\theta$ , the radius  $R_o$  of the inside diameter of the receiving section 58 is set larger than the radius  $R_i$  of the spherical inner surface of the retainer 4 ( $R_o > R_i$ ).

【0031】

In the foregoing structure, when a serration shaft section of the connecting shaft 5 and the inner joint member 2 are coupled by serrations and attaching a snap ring 59 completely couples both (refer to Figs. 2 and 3), the press section 52 of the plunger unit 50 and the receiving section 58 of the receiver member 56 come into contact with each other, and then the ball 53 is retracted and the compression coil spring 54 is compressed. Since the position of the plunger unit 50 is fixed with respect to the axial end surface of the connecting shaft 5, as described above, it is possible to always keep the contact state between the press section 52 and the receiving section 58 by stabilizing the attachment state of the press section 52, and hence pressure from the press section 52 can securely act on the receiving section 58.

【0032】

Fig. 4 shows the retainer 4. The retainer 4 is provided with six window-shaped pockets 4a for containing and holding the torque transmission balls 3 and pillar sections 4d between the pockets 4a adjoining in the circumferential direction. In this embodiment, the circumferential lengths of each pocket 4a are

all equal. The difference ( $= L - d$ ) between the axial dimension  $L$  of the pocket 4a and the diameter  $d$  of the torque transmission ball 3 at the start of operation of the joint, that is, the axial initial clearance between them is controlled in a range of 0 to + 50  $\mu\text{m}$ , and more preferably in a range of 0 to + 30  $\mu\text{m}$ . The retainer 4 is made of, for example, carburized steel which has a carburized layer in its surface due to carburizing and quenching. Chrome steel, chromium molybdenum steel, nickel chrome molybdenum steel, or the like is available as the carburized steel.

【 0 0 3 3 】

As shown in Fig. 5 in enlargement, the pocket 4a of the retainer 4 comprises a pair of axial walls 4a1 opposed in the axial direction of the retainer 4, a pair of circumferential walls 4a2 opposed in the circumferential direction, and corner round sections 4a3 connecting the axial wall 4a1 and the circumferential wall 4a2. In this embodiment, the ratio ( $R/d$ ) of the radius of curvature  $R$  of the corner round section 4a3 to the diameter  $d$  of the torque transmission ball 3 is set in a range of  $0.45 \leq R/d \leq 0.62$ . Also, the circumferential wall 4a2 and the corner round sections 4a3 are drawn in a single arc with the radius of curvature  $R$ . Furthermore, as to the axial walls 4a1, grinding, cutting by quenched steel, or the like is carried out after the heat treatment (carburizing and quenching) of the retainer 4 in order to reduce variations in a processing margin (the circumferential walls 4a2 and the corner round sections 4a3 are remained as-is after a cutting process by press).

【BRIEF DESCRIPTION OF THE DRAWINGS】

【 0 0 3 4 】

Fig. 1 is a longitudinal sectional view of a constant velocity universal joint for steering to which the present invention is applied;

Fig. 2 is a sectional view of a plunger unit section;

Fig. 3 is an enlarged sectional view of the plunger unit section;

Fig. 4(a) is a cross sectional view of a retainer;

Fig. 4(b) is a longitudinal sectional view of a retainer;

Fig. 5 is an enlarged plan view showing the periphery of a pocket of the retainer;

Fig. 6 is a graph showing the relationship between a ratio ( $R/d$ ) and a maximum principal stress load of a pillar section;

Fig. 7(a) is a plan view of a steering device;

Fig. 7(b) is a side view of the steering device;

Fig. 7(c) is a perspective view of the steering device;

Fig. 8(a) is a longitudinal sectional view showing a conventional constant velocity universal joint;

Fig. 8(b)} is a cross sectional view showing a conventional constant velocity universal joint;

Fig. 9(a) is a longitudinal sectional view of a conventional retainer; and

Fig. 9(b) is an enlarged plan view showing the periphery of a pocket in the conventional joint.

**【Explanation of numerals】**

**【0035】**

- 1 outer member
- 1 a track groove
- 1 b inner diameter surface
- 2 inner joint member (inner member)
- 2 a track groove
- 2 b outer diameter surface
- 2 d engagement section
- 3 torque transmission ball
- 4 retainer
- 4 a pocket
- 4 b outer diameter surface
- 4 c inner diameter surface

4 d pillar section  
4 a 1 axial wall  
4 a 2 circumferential wall  
4 a 3 corner round section  
5 connecting shaft (inner member)  
5 a recessed section  
5 b axial end surface  
1 1 outer member  
1 1 a inner diameter surface  
1 1 b track groove  
1 2 inner joint member  
1 2 a outer diameter surface  
1 2 b track groove  
1 2 c engagement section  
1 3 torque transmission ball  
1 4 retainer  
1 4 c pocket  
1 4 d pillar section  
1 4 c 1 axial wall  
1 4 c 3 corner round section  
1 4 c 4 straight section  
4 0 yoke  
5 0 plunger unit  
5 2 press section  
5 3 ball  
5 5 case  
5 5 a engaged section  
5 5 b flange  
5 6 receiver member



5 6 a spherical section  
5 6 b attachment section  
5 8 receiving section  
5 9 snap ring  
6 1 shaft couplings  
6 2 steering shaft  
6 6 steering wheel  
6 8 steering gear  
6 9 tie rod